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A (SEMI-)PARAMETRIC FUNCTIONAL COEFFICIENT AUTOREGRESSIVE CONDITIONAL DURATION MODEL

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ABSTRACT: In this paper, we propose a class of ACD-type models that accommodates overdispersion, intermittent dynamics, multiple regimes, and sign and size asymmetries in financial durations. In particular, our functional coefficient autoregressive conditional duration (FC-ACD) model relies on a smooth-transition autoregressive specification. The motivation lies on the fact that the latter yields a universal approximation if one lets the number of regimes grows without bound. After establishing that the sufficient conditions for strict stationarity do not exclude explosive regimes, we address model identifiability as well as the existence, consistency, and asymptotic normality of the quasi-maximum likelihood (QML) estimator for the FC-ACD model with a fixed number of regimes. In addition, we also discuss how to consistently estimate using a sieve approach a semiparametric variant of the FC-ACD model that takes the number of regimes to infinity. An empirical illustration indicates that our functional coefficient model is flexible enough to model IBM price durations.

KEYWORDS: explosive regimes, neural networks, quasi-maximum likelihood, sieve estimation, smooth transition, stationarity.

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1. INTRODUCTION

There has recently been a great interest in the implications of price durations in empirical finance. Most empirical analyses use one of the several extensions of Engle and Russell’s (1998) linear autoregressive conditional duration (ACD) model that abound in the literature. Fernandes and Grammig (2006) consider a family of ACD-type models that relies on asymmetric responses to shocks and on a Box-Cox transformation to the conditional duration process. Their family encompasses most ACD-type models in the literature, though there are a few exceptions. Zhang, Russell and Tsay (2001) argue for a nonlinear version based on self-exciting threshold ACD processes, whereas Meitz and Teräsvirta (2006) propose the smooth transition and the time-varying ACD models. This paper puts forward a novel class of ACD-type models based on logistic smooth-transition autoregressive processes with multiple regimes. In particular, our functional coefficient autoregressive conditional duration (FC-ACD) model not only nests the ACD-type processes proposed by Meitz and Teräsvirta (2006), but may also serve as the basis for a semiparametric approach if one lets the number of regimes to grow without bounds.

We first address the theoretical aspects of the FC-ACD process with a fixed number of regimes. In particular, we establish sufficient conditions for strict stationarity and for the existence of higher-order moments. It turns out that the conditions are quite mild in that they do not exclude duration processes with explosive regimes. As in Medeiros and Veiga (2009), we show that explosive regimes may entail very interesting dynamics. In particular, strictly stationary FC-ACD processes with explosive regimes are particularly suitable to model intermittent dynamics: The system spends a large fraction of time in a bounded region, but sporadically develops an instability that grows exponentially for some time and then suddenly collapses.
We then move to establishing sufficient conditions for model identifiability as well as for the existence, consistency, and asymptotic normality of the quasi-maximum likelihood (QML) estimator. We derive consistency and asymptotic normality under first- and second-order moment conditions, respectively. Finally, we develop a sequence of simple Lagrange multiplier (LM) tests to determine the number of limiting regimes. Although we derive the tests using the exponential distribution as reference, we also discuss a robust version so as to cope with non-exponential errors.

We also consider a semiparametric version of the FC-ACD model in which the number of extra regimes \( M \) increases with the sample size. The motivation rests on the fact that the logistic smooth transition autoregressive process with \( M \to \infty \) acts as a universal neural-network approximation (Hornik, Stinchcombe and White, 1989). The resulting semiparametric model encompasses most first-order ACD-type models in the literature, despite the fact we impose some restrictions on the functional coefficients specification to achieve identification of the nonparametric term as well as to ensure stationarity and geometric ergodicity. To estimate the semiparametric model, we rely on a regularization procedure that penalizes the log-likelihood function as one increases the number of regimes. In particular, we employ Chen and Shen’s (1998) results to provide asymptotic justification for the resulting sieve estimator.

We thus deem that we contribute to the literature in several aspects. First, in contrast to Meitz and Teräsvirta’s (2006) smooth transition ACD framework, our FC-ACD specification permits modeling more than two limiting regimes as well as explosive regimes. Second, our framework allows for statistical inference as to what concerns the number of regimes, and hence it is not necessary to impose a priori a certain number of regimes as in Zhang et al. (2001). Third, we also consider the case in which the number of regimes to increase with the sample size, so as to obtain a sieve approximation for the conditional duration process. Finally, we demonstrate the practical usefulness of the FC-ACD specification by modeling IBM price durations. The main
motivation lies on the fact that early findings clearly reject many of the extant ACD-type specifications in the literature (see Fernandes and Grammig, 2006). We show that allowing for multiple regimes facilitates substantially the task of reaching a congruent specification for the IBM price durations.

The remainder of the paper is organized as follows. Section 2 outlines the statistical properties of the FC-ACD process, whereas Section 3 deals with quasi-maximum likelihood estimation for a known fixed number of regimes. Section 4 then proposes a sequential testing procedure to determine the unknown number of regimes. Section 5 next considers a semiparametric version of the FC-ACD model by letting the number of regimes increase with the sample size. Section 6 collects the findings of the empirical application that we carry out aiming to model IBM price durations. Section 7 summarizes the main results and offers some concluding remarks. We collect all technical details concerning the derivations, including proofs and lemmas, in the Appendix.

2. A FUNCTIONAL COEFFICIENT ACD PROCESS

Let the duration \( x_i = t_i - t_{i-1} \) denote the time spell between two events occurring at times \( t_i \) and \( t_{i-1} \). For instance, we define price duration as the time interval necessary to observe a cumulative change in the mid-price of at least some given value. To account for the serial dependence that characterizes financial duration data, we assume that durations follow an accelerated time failure process.

ASSUMPTION 1. Let \( x_i = \psi_i \epsilon_i \). The sequence \( \{\epsilon_i; \ i \in \mathbb{Z}\} \) of iid random variables has a continuous density function \( f > 0 \) in \([0, \infty)\), with \( \mathbb{E} (\epsilon_i \mid \mathcal{F}_{i-1}) = 1 \), where \( \mathcal{F}_{i-1} \) is the information set available at time \( t_{i-1} \). Also, \( \psi_i = \mathbb{E} (x_i \mid \mathcal{F}_{i-1}) \) is independent of \( \{\epsilon_i, \epsilon_{i+1}, \ldots\} \).

Assumption 1 is standard in the literature (see discussion in Drost and Werker, 2004). Engle and Russell’s (1998) ACD model assumes a linear specification for the
conditional expected duration, viz. $\psi_i = \omega + \alpha x_{i-1} + \beta \psi_{i-1}$. Bauwens and Giot (2000) propose a logarithmic version of the ACD model with a similar autoregressive structure for the log rather than for the level of the expected duration so as to ensure the positivity of the duration process. In this paper, we propose a more flexible model based on a functional coefficient specification.

**Definition 1.** The duration $x_i$ follows a functional coefficient autoregressive conditional duration (FC-ACD) process with $M+1$ regimes if $x_i = \psi_i \epsilon_i$, where $\epsilon_i$ and $\psi_i$ satisfy Assumption 1 and

$$\log \psi_i = \omega(\log x_{i-1}) + \alpha(\log x_{i-1}) \log x_{i-1} + \beta(\log x_{i-1}) \log \psi_{i-1}$$  \hspace{1cm} (1)

with

$$\omega(\log x_i) = \omega_0 + \sum_{m=1}^{M} \omega_m G_m(\log x_i)$$  \hspace{1cm} (2)

$$\alpha(\log x_i) = \alpha_0 + \sum_{m=1}^{M} \alpha_m G_m(\log x_i)$$  \hspace{1cm} (3)

$$\beta(\log x_i) = \beta_0 + \sum_{m=1}^{M} \beta_m G_m(\log x_i),$$  \hspace{1cm} (4)

and

$$G_m(\log x_i) = G(\log x_i; \gamma_m, c_m) = \frac{1}{1 + \exp \left[ -\gamma_m \left( \log x_i - c_m \right) \right]}.$$  \hspace{1cm} (5)

The FC-ACD process belongs to the class of logistic smooth transition autoregressive models. The parameter vector is

$$\theta = (\omega_0, \ldots, \omega_M, \alpha_0, \ldots, \alpha_M, \beta_0, \ldots, \beta_M, c_1, \ldots, c_M, \gamma_1, \ldots, \gamma_M)^T.$$  

The slope parameters $\gamma_m$ ($m = 1, \ldots, M$) control the smoothness of the regime transitions: e.g., $G_m(\log x_i)$ converges to a step function as $\gamma_m$ grows without bound. Equation (5) also implies that log-durations determine the weights at which each regime contributes to the overall dynamics of the process at time $t_i$. Alternatively, one may could think of distinct transition variables, e.g., the log of the expected duration. The
resulting model thus is quite similar to Zhang et al.’s (2001) self-exciting threshold ACD specification. The main differences are that we allow for smooth transitions and that, as in Bauwens and Giot (2000), we model the log rather than the level of the expected duration so as to avoid positivity constraints on the parameter space.

The FC-ACD specification entails several advantages. First, the condition we derive in Subsection 2.1 for strict stationarity does not rule out the presence of explosive regimes. The latter is interesting because it may give way to the moderately high, but very persistent, autocorrelation structure that seems to characterize financial duration data. Second, our specification nests the threshold ACD-type processes put forth by Meitz and Teräsvirta (2006). Third, as in Medeiros and Veiga (2000), one may interpret (2) to (4) as a single-hidden layer neural network with $M$ hidden units. It thus follows that the FC-ACD specification admits a semiparametric variant by letting the number of regimes increase with the sample size. A neural network with a large number of hidden units indeed approximates arbitrarily well any Borel-measurable function (Hornik et al., 1989).

To establish the statistical properties of the FC-ACD process, we require a standard regularity condition on the error term and on the parameter space.

**ASSUMPTION 2.** The error term $\epsilon_i$ is such that $E|\log \epsilon_i| < \infty$ and $E|\epsilon_i|^k < \infty$ for some integer $k \geq 4$.

**ASSUMPTION 3.** The vector $\theta$ is interior to the compact parameter space $\Theta \subseteq \mathbb{R}^{5M+3}$.

The asymptotic normality of the QML estimator depends heavily on the fourth-moment requirement in Assumption 2. If the interest lies only on the consistency of the QML estimator, then it suffices to assume that the finiteness of the second moment.

2.1. **Statistical properties: Strict stationarity and geometric ergodicity.** Let $u_i = (\log \psi_i, \log \epsilon_i)'$. It is easy to see that $\{u_i; i \in \mathbb{Z}\}$ is a Markov chain with homogenous
transition probability in view that
\[ u_{i+1} = F(u_i; \theta) + \epsilon_{i+1}, \tag{6} \]
where \( F(u_i; \theta) = [F(u_i; \theta), 0]' \) with
\[ F(u_i; \theta) = \omega (\log x_i) + [\alpha (\log x_i) + \beta (\log x_i)] \log x_i + \alpha (\log x_i) \log \epsilon_i, \]
and \( \epsilon_i = [0, \log \epsilon_i]' \). We are now ready to establish our first theoretical result.

**Theorem 1.** Suppose that the duration \( x_i \) follows a FC-ACD process with \( M + 1 \) regimes satisfying Assumptions 1 and 2. If \( A_0 < 1, A_M < 1, \) and \( A_0 A_M < 1 \), where \( A_0 = \alpha_0 + \beta_0 \) and \( A_M = \sum_{m=0}^{M} (\alpha_m + \beta_m) \), then strict stationarity and geometric ergodicity hold for the duration process and \( \mathbb{E} |\log x_i|^{k} < \infty \), with \( k \) as in Assumption 2.

The sufficient condition in Theorem 1 is intuitive and simple despite not only the highly nonlinear nature of the model but also the extant sufficient conditions in the literature (Meitz, 2006; Fernandes and Grammig, 2006; Meitz and Saikkonen, 2008). As in threshold autoregressive models (Tong, 1990), it suffices to impose constraints only on the two polar regimes. In particular, it allows strictly stationary and ergodic FC-ACD processes to have explosive regimes. This is of particular interest given that such processes are suitable to model intermittent dynamics (Medeiros and Veiga, 2009).

An ergodic FC-ACD process with explosive regimes indeed spends a large fraction of time in a bounded region, though it sporadically develops an instability that grows exponentially for some time and then suddenly collapses. As we illustrate in Example 1, even though we only consider first-order specifications, the FC-ACD process admits a highly persistent behavior with moderate values for the autocorrelation function, especially in the presence of explosive regimes.

**Example 1.** Consider a FC-ACD process with three limiting regimes, exponential errors, and parameters \( \omega_0 = 0.005, \omega_1 = -0.9, \omega_2 = 3, \alpha_0 = 0.09, \alpha_1 = -0.05, \alpha_2 = -0.05, \beta_0 = 0.9, \beta_1 = 0.6, \beta_2 = -0.5, \gamma_1 = 1000, \gamma_2 = 100, c_1 = -2, \) and
Figure 1. Simulated path and autocorrelation function of a FC-ACD process with three limiting regimes, exponential errors, and parameters $\omega_0 = 0.005$, $\omega_1 = -0.9$, $\omega_2 = 3$, $\alpha_0 = 0.09$, $\alpha_1 = -0.05$, $\alpha_2 = -0.05$, $\beta_0 = 0.9$, $\beta_1 = 0.6$, $\beta_2 = -0.5$, $\gamma_1 = 1000$, $\gamma_2 = 100$, $c_1 = -2$, and $c_2 = 1$. The condition for strict stationarity holds given that $A_0 = \alpha_0 + \beta_0 = 0.99$, $A_2 = \sum_{m=0}^{2} (\alpha_m + \beta_m) = 0.99$ and $A_0 A_2 = 0.9801$, despite the explosiveness of the second regime. Figure 1 depicts a simulated path of such duration process and the corresponding autocorrelation function up to the 200th lag.

3. QUASI-MAXIMUM LIKELIHOOD ESTIMATION

In this section, we carefully address the parametric estimation of the FC-ACD model. To avoid further distributional assumptions, we invoke quasi-maximum likelihood (QML) methods. After describing the setting, we derive the conditions for model
identification as well as for the consistency and asymptotic normality of the QML estimator.

The derivation of the semiparametric ACD model in Drost and Werker (2004) clarifies that adaptiveness occurs if and only if the error distribution belongs to the two-parameter gamma family with unit mean. It actually turns out that the exponential and gamma scores are proportional, and hence there is no efficiency loss in restricting attention to the exponential distribution. This means that the QML estimator is consistent only if we write the likelihood as if under the assumption of exponential (or standard gamma) distribution (Bickel, 1982). The quasi-log-likelihood thus reads

$$L_N(\theta) = \frac{1}{N} \sum_{i=1}^{N} \ell_i(\theta),$$

(7)

where

$$\ell_i(\theta) = - \log \psi_i - \frac{x_i}{\psi_i}.$$  

We treat the unobservable sequence $$\{(x_{-i}, \psi_{-i}) ; i \in \mathbb{N}\}$$ as constant rather than random. The quasi-log-likelihood is thus suitable for practical applications given that it is not conditional on the true initial value $$(x_0, \psi_0)$$.

To derive the asymptotic properties of the QML estimator, it is convenient to work also with the unobserved process $$\{(x_{u,i}, \psi_{u,i}) ; i \in \mathbb{Z}\}$$, which satisfies

$$x_{u,i} = \psi_{u,i} \epsilon_{u,i}$$

$$\log \psi_{u,i} = \omega_0 + \alpha_0 \log x_{u,i-1} + \beta_0 \log \psi_{u,i-1}$$

$$+ \sum_{m=1}^{M} \left[ \omega_m + \alpha_m \log x_{u,i-1} + \beta_m \log \psi_{u,i-1} \right] G_m(\log x_i).$$

(8)

The unobserved quasi-log-likelihood conditional on $$\mathcal{F}_0 = (x_0, x_{-1}, x_{-2}, \ldots)$$ is

$$L_{u,N}(\theta) = \frac{1}{N} \sum_{i=1}^{N} \ell_{u,i}(\theta),$$

(9)

with $$\ell_{u,i}(\theta) = - \log \psi_{u,i} - \frac{x_{u,i}}{\psi_{u,i}}$$. As is apparent, the primary difference between $$L_N(\theta)$$ and $$L_{u,N}(\theta)$$ is that the latter is conditional on an infinite series of past observations. For the same technical reasons, we also consider the unfeasible QML estimator.
based on (9). Let
\[ \hat{\theta}_N = \arg\max_{\theta \in \Theta} L_N(\theta) = \arg\max_{\theta \in \Theta} \frac{1}{N} \sum_{i=1}^{N} \ell_i(\theta), \] (10)
and
\[ \hat{\theta}_{u,N} = \arg\max_{\theta \in \Theta} L_{u,N}(\theta) = \arg\max_{\theta \in \Theta} \frac{1}{N} \sum_{i=1}^{N} \ell_{u,i}(\theta). \] (11)

Subsection 3.1 next discusses the existence of \( L(\theta) = \mathbb{E} [\ell_{u,i}(\theta)] \), so as to tackle the identifiability of the FC-ACD model in Subsection 3.2. Subsection 3.3 then derives the consistency and asymptotic normality of the QML estimators in (10) and (11) under second- and fourth-order moment conditions, respectively.

3.1. Existence of the QML estimator. It is easy to appreciate that the QML estimator exists only if \( L(\theta) = \mathbb{E} [\ell_{u,i}(\theta)] \) exists. The next result immediately follows from White’s (1996) Theorem 2.12, which establishes that \( L(\theta) \) exists under certain continuity and measurability conditions on the quasi-log-likelihood function.

**Theorem 2.** If the duration \( x_i \) follows a strictly stationary and ergodic FC-ACD process with \( M + 1 \) regimes, then, for any parameter vector \( \theta \in \Theta \), \( L(\theta) \) exists and is finite under Assumptions 1 and 3.

3.2. Identifiability of the model. A fundamental problem that usually haunts nonlinear econometric models is the lack of identifiability of the empirical loss function. To carry out statistical inference, we must first show that \( \theta_0 \) is the unique maximizer of \( L(\theta) \). It turns out, however, that we achieve neither global nor local identification of the FC-ACD model without imposing some parametric constraints.

There are three reasons for the model unidentifiability. First, as the multiple regimes correspond to hidden units in neural networks, they are interchangeable. This means that the empirical loss function of the FC-ACD specification is invariant to regime permutations, and hence there are \((M + 1)!\) equal local maxima for the quasi-log-likelihood in (7). See Sussman (1992) and Suarez-Fariñas, Pedreira and Medeiros.
(2004) for a discussion. Second, the logistic function in (5) is such that

\[ G(\log x_i; \gamma_m, c_m) = 1 - G(\log x_i; -\gamma_m, c_m). \]

This property evidently compromises model identifiability. Third, identifiability also relates to model reducibility as it automatically imposes constraints on the vector of parameters \( \theta_m = (\omega_m, \alpha_m, \beta_m, \gamma_m, c_m)' \) that defines the extra regimes of the FC-ACD model \( m = 1, \ldots, M \). For instance, it is not possible to identify the logistic parameters \( (\gamma_m, c_m) \) if \( (\omega_m, \alpha_m, \beta_m)' = 0 \), whereas \( (\omega_m, \alpha_m, \beta_m, c_m)' \) may take on any value without affecting the value of the quasi-log-likelihood function if \( \gamma_m = 0 \).

We then restrict the parameter space \( \Theta \) so as to circumvent such problems.

**ASSUMPTION 4.** The parameter space \( \Theta \) is such that any vector \( \theta \in \Theta \) satisfies

- **C1:** \( c < c_1 < \ldots < c_M < \bar{c} \) for some finite constants \( c \) and \( \bar{c} \);
- **C2:** \( \gamma_m > 0 \) for \( m = 1, \ldots, M \) and
- **C3:** \( (\omega_m, \alpha_m, \beta_m) \neq 0 \) for some \( m \in \{0, \ldots, M\} \).

**THEOREM 3.** Assumptions 1 to 4 ensure the global identifiability of the FC-ACD model and that \( \mathcal{L}(\theta) \) has a unique maximum at \( \theta_0 \).

Despite the fact that Assumption 4 is not verifiable, one may alleviate the risk of irrelevant regimes by carrying out a sequence of LM tests (see Section 4).

3.3. **Asymptotic theory.** Our interest lies on the large sample properties of the QML estimator given by (10). To derive the next result, we first establish that the unfeasible QML estimator in (11) converges in probability to \( \theta_0 \) and then show that the difference between the two QML estimators shrinks to zero as the sample size \( N \) grows without bound.

**THEOREM 4.** Under Assumptions 1 to 4, the QML estimators in (10) and (11) are consistent, i.e., \( \hat{\theta}_{u,N} \xrightarrow{p} \theta_0 \) and \( \hat{\theta}_N \xrightarrow{p} \theta_0 \), for strictly stationary FC-ACD models.
To complete the asymptotic characterization of the QML estimator, we first introduce some notation and then establish the asymptotic distribution of the QML estimator. Let

$$A_0 = \mathbb{E} \left[ - \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} \right]_{\theta_0},$$

$$B_0 = \frac{1}{N} \sum_{i=1}^{N} \mathbb{E} \left( \frac{\partial \ell_{u,i}(\theta)}{\partial \theta} \frac{\partial \ell_{u,i}(\theta)}{\partial \theta'} \right)_{\theta_0},$$

and denote their empirical counterparts by

$$A_N(\theta) = \frac{1}{N} \sum_{i=1}^{N} \left[ \frac{\partial^2 \log \psi_i}{\partial \theta \partial \theta'} \left( 1 - \frac{x_i}{\psi_i} \right) + \frac{x_i}{\psi_i} \frac{\partial \log \psi_i}{\partial \theta} \frac{\partial \log \psi_i}{\partial \theta'} \right],$$

$$B_N(\theta) = \frac{1}{N} \sum_{i=1}^{N} \left( \frac{x_i}{\psi_i} - 1 \right)^2 \frac{\partial \log \psi_i}{\partial \theta} \frac{\partial \log \psi_i}{\partial \theta'}.$$

We are now ready to state that the QML estimator weakly converges to a Gaussian distribution with the usual asymptotic covariance matrix (White, 1982).

**Theorem 5.** Under the conditions we assume in Theorem 4, it follows that

$$\sqrt{N} \left( \hat{\theta}_N - \theta_0 \right) \xrightarrow{d} \mathcal{N} \left( 0, A_0^{-1}B_0A_0^{-1} \right) \quad (12)$$

and that $A_N(\hat{\theta}_N)$ and $B_N(\hat{\theta}_N)$ consistently estimate $A_0$ and $B_0$, respectively.

### 3.4. Optimization algorithm.

As in any smooth-transition specification, the likelihood function of the FC-ACD model is very likely flat, especially for the transition parameters. This means that one must carry out the optimization in a very careful fashion. That is why we initially employ a genetic algorithm based on a population of 500 sets of initial values for the parameters that meet the strict stationarity conditions in Theorem 1. We then switch to the BFGS nonlinear-optimization algorithm using as initial values the solution of the genetic-algorithm procedure.

### 4. Determining the number of regimes

As the FC-ACD specification in Definition 1 depends on the unknown number of extra regimes $M$, statistical inference must come into play. One solution is to carry out
a sequential procedure in which we start with a small model and then decide whether it pays off to add more regimes using some model selection criterion. This typically boils down to some sort of likelihood ratio testing, where the particular choice of the model selection criterion determines the asymptotic significance level of the test (see Teräsvirta and Mellin, 1986).

There is a serious drawback in such approach, however. Suppose the data generating mechanism is a FC-ACD process with $M$ regimes. Applying a model selection criterion to decide whether to consider $M + 1$ regimes requires the estimation of an unidentified model with $M$ logistic functions. It thus is impossible to estimate the parameters in a consistent manner, so that numerical problems likely arise in the QML estimation. Besides, the lack of identification under the alternative hypothesis of $M + 1$ regimes also contaminates the likelihood ratio statistic, which does not converge to the usual $\chi^2$ distribution under the null hypothesis of $M$ regimes.

We therefore take a different approach to determining the number of regimes of the FC-ACD model. Although we keep relying on a specific-to-general modeling strategy, we circumvent the identification problem using sequential LM-type tests. Our sequential testing procedure controls for the significance level of the individual tests using Bonferroni’s upper bound for the overall significance level. In what follows, we discuss our framework assuming exponential errors and then show how to robustify the procedure so as to cope with nonexponential errors.

Consider an ergodic FC-ACD process with $M + 1$ regimes as in (1)–(5). To test whether it is necessary to include the term corresponding to the $(M + 1)$th regime, viz.

$$(\omega_M + \alpha_M \log x_{i-1} + \beta_M \log \psi_{i-1}) G_M(\log x_{i-1}; \gamma_M, c_M),$$

we define the null and alternative hypotheses as $\mathbb{H}_M: \gamma_M = 0$ and $\mathbb{H}_{M+1}: \gamma_M > 0$, respectively. To remedy the lack of identification of the FC-ACD model with $M + 1$ regimes under the null, we expand the logistic function $G_M$ around $\gamma_M = 0$ as in Meitz and Teräsvirta (2006).
A first-order Taylor expansion of $G_M$ around $\gamma_M = 0$ then yields

$$\log \psi_i = \tilde{\omega}_0 + \tilde{\alpha}_0 \log x_{i-1} + \tilde{\beta}_0 \log \psi_{i-1}$$

$$+ \sum_{m=1}^{M-1} [\omega_m + \alpha_m \log x_{i-1} + \beta_m \log \psi_{i-1}] G_m(\log x_{i-1})$$

$$+ \delta_1 \log \psi_{i-1} \log x_{i-1} + \delta_2 (\log x_{i-1})^2 + O(\gamma_M^2),$$

where $\tilde{\omega}_0 = \omega_0 + \frac{1}{2} \omega_M - \frac{1}{4} \omega_M \gamma_M c_M$, $\tilde{\alpha}_0 = \alpha_0 + \frac{1}{2} \alpha_M + \frac{1}{4} \gamma_M (\omega_M - \alpha_M c_M)$. $\tilde{\beta}_0 = \beta_0 + \frac{1}{2} \beta_M - \frac{1}{4} \beta_M \gamma_M c_M$, $\delta_1 = \frac{1}{4} \beta_M \gamma_M$, and $\delta_2 = \frac{1}{4} \alpha_M \gamma_M$. Under the null of $H_M: \gamma_M = 0$, the specification in (14) reduces to the FC-ACD model with $M$ regimes.

Before stating the next result, we first establish some notation. Let $\phi = [\theta', \delta']'$ with $\delta = (\delta_1, \delta_2)'$. The QML estimator of $\phi$ under the null hypothesis of $H_M: \gamma_M = 0$ is $\hat{\phi}_N = [\hat{\theta}_N, 0]$. Let $\hat{\psi}_i \equiv \psi_i (\hat{\phi}_N)$ denote the estimate of the expected conditional duration under the null and $\hat{d}_i = \frac{\partial \log \psi_i}{\partial \phi}|_{\phi = \hat{\phi}_N}$ correspond to the derivative of $\log \psi_i$ with respect to $\phi$ evaluated at the QML estimator $\hat{\phi}_N$. Although $\hat{d}_i$ is recursive in that it depends on $\hat{d}_{i-1}$, it is straightforward to calculate it as a function of the initial value $x_0$ of the duration process as in Medeiros and Veiga (2009). We are now ready to state the asymptotic distribution of the LM statistic to test $H_M: \gamma_M = 0$ against $H_{M+1}: \gamma_M > 0$.

**Theorem 6.** Let the duration $x_i$ follow a strictly stationary and ergodic FC-ACD process with $M$ regimes. Assumptions 1 to 4 ensure that

$$LM = N \left[ \sum_{i=1}^{N} \left( \frac{x_i}{\psi_i} - 1 \right) \hat{d}_i \right] \left( \sum_{i=1}^{N} \hat{d}_i \hat{d}_i' \right)^{-1} \left[ \sum_{i=1}^{N} \left( \frac{x_i}{\psi_i} - 1 \right) \hat{d}_i \right]$$

has an asymptotic $\chi^2_2$ distribution under the null of $H_M: \gamma_M = 0$.

To avoid the exponential assumption, one may consider a robust version of the LM test that is suitable to nonexponential errors, as in Meitz and Teräsvirta (2006), using the tools in Wooldridge (1990, Procedure 4.1). The three steps of the resulting robust testing procedure are as follows.

1. Estimate the FC-ACD model under the null (with $M$ regimes).
(2) Regress \( \frac{\partial}{\partial \theta} \log \psi_i |_{\phi=\hat{\phi}_N} \) on \( \frac{\partial}{\partial \theta} \log \psi_i |_{\phi=\hat{\phi}_N} \) and compute the vector of residuals \( \hat{\epsilon}_i \) for \( i = 1, \ldots, N \).

(3) Regress 1 on \( \left( \frac{x_i}{\hat{\psi}_1} - 1 \right) \hat{\epsilon}_i \) and compute the resulting sum of squared residuals \( SSR \). The robust test statistic \( LM_R = N - SSR \) has an asymptotic \( \chi^2 \) distribution under the null hypothesis of \( \mathbb{H}_M \).

We now combine the above statistical ingredients into a coherent modeling strategy that involves a sequence of robust LM tests. The idea is to test a FC-ACD model with only one regime against an alternative model with two regimes at the significance level \( \lambda_1 \). In the event we reject the null, we keep testing FC-ACD specifications with \( J \) regimes against alternative models with \( J + 1 \) regimes at the significance level \( \lambda_J = \lambda_1 C^{1-J} \) for some arbitrary constant \( C > 1 \). We terminate the testing sequence at the first nonrejection outcome and then estimate the number of extra regimes \( M \) of the FC-ACD specification by \( \hat{M} = J - 1 \), where \( J \) refers to how many testing runs are necessary to lead to the first nonrejection result. By reducing the significance level at each step of the sequence, we are able to control the overall significance level and hence to avoid excessively large models. The Bonferroni procedure indeed ensures that such sequence of robust LM tests is consistent and that \( \sum_{J=1}^{\tilde{J}} \lambda_J \) acts as an upper bound for the overall significance level. As for the selection of the arbitrary constant \( C \), it is good practice to carry out the sequential testing procedure with different values of \( C \) so as to avoid models that are too parsimonious.

5. A SEMIPARAMETRIC VARIANT

In this section, we take benefit from the fact that the logistic smooth transition autoregressive specification in (2) to (4) corresponds to a single-hidden layer neural network with \( M \) hidden units. This implies that, if \( M \) is large enough, it approximates arbitrarily well any Borel-measurable function (Hornik et al., 1989; Chen and White, 1998). We therefore consider a semiparametric version of the FC-ACD model in which the number of extra regimes \( M \) increases with the sample size. To emphasize
the dependence on the sample size, we denote the number of extra regimes by $M_n$ in this section.

**Definition 2.** The duration $x_i$ follows a semiparametric FC-ACD process if $x_i = \psi_i \epsilon_i$, where $\epsilon_i$ and $\psi_i$ satisfy Assumption 1 with $\sigma^2 = \mathbb{E} \log \epsilon_i^2 \leq \infty$ and

$$
\log \psi_i = \omega(\log x_{i-1}) + \beta \log \psi_{i-1}
$$

with $|\beta| < 1$ and $\omega(\cdot) < \infty$ belonging to the functional space $\mathcal{H}$ of continuous bounded functions with finite first absolute moments of the Fourier magnitude distributions.

This definition complements well Drost and Werker’s (2004) semiparametric approach, whose focus is on the error distribution rather than on the specification of the conditional expected duration. It indeed encompasses most first-order ACD-type models in the literature, despite the fact that we impose three restrictions on the functional coefficients specification. First, we confine attention to duration processes that satisfy strict stationarity with finite second moments, geometric ergodicity, and $\beta-$mixingness with exponential decay by assuming that $\omega(\cdot)$ is bounded and that $|\beta| < 1$ (see Meitz and Saikkonen, 2008). This ensure that we may apply Chen and Shen’s (1998) asymptotic theory for sieve extremum estimates under weak dependence.

Second, we eliminate the slope functional coefficient in (1) — i.e., $\alpha(z) z$ — to achieve identification of the nonparametric component in (16). Third, we restrict the recursiveness of the conditional expected duration process by assuming that $\beta$ is constant across regimes. This simplifies matters a lot for it permits rewriting the semiparametric FC-ACD model as a tractable nonlinear AR model of infinite order, namely,

$$
\log x_i = \omega(\log x_{i-1}) + \beta \log \psi_{i-1} + \log \epsilon_i \\
= \sum_{j=0}^{\infty} \beta^j \omega(\log x_{i-1-j}) + \log \epsilon_i.
$$

(17)
As the largeness of the functional space $\mathcal{H}$ may compromise the estimation, we approximate $\mathcal{H}$ with a sequence $\mathcal{H}_N$ of sieve spaces (Grenander, 1981; Chen and Shen, 1998) that becomes dense in $\mathcal{H}$ as the sample size increases. As the sieve spaces correspond to finite-dimensional parameter spaces, they only require parametric estimation. In particular, we approximate the function $\omega \in \mathcal{H}$ with $\omega_N \in \mathcal{H}_N$, where

$$\omega_N(\cdot) = \omega_0^{(N)} + \sum_{m=1}^{M_N} \omega_m^{(N)} G_m^{(N)}(\cdot)$$  \hspace{1cm} (18)

and $G_m^{(N)}(\cdot)$ is the logistic function in (5) with finite parameters $c_m^{(N)}$ and $\gamma_m^{(N)}$. We restrict the parameter space so that $\sum_{m=0}^{M_N} |\omega_m^{(N)}| \leq c$, $|c_m^{(N)}| \leq c$, and $|\gamma_m^{(N)}| \leq c$ for some generic constant $c < \infty$. Makovoz (1996) demonstrates that the approximation error is such that $\|\omega_N - \omega\| = O\left(M_N^{-1}\right)$, where $\|\cdot\|$ denotes the $L^2$ norm.

The resulting vector of parameters then is

$$\theta^{(N)} = \left(\omega_0^{(N)}, \ldots, \omega_{M_N}^{(N)}, c_1^{(N)}, \ldots, c_{M_N}^{(N)}, \gamma_1^{(N)}, \ldots, \gamma_{M_N}^{(N)}, \beta\right).$$

Instead of alluding to the sequence $\mathcal{H}_N$ of sieve functional spaces, we sometimes refer to the corresponding sequence $\Theta^{(N)}$ of sieve parameter spaces so as to emphasize the parametric nature of the estimation problem. In accordance with the sieve literature, we then approximate the first term of the right-hand side of (17) by

$$\log \psi_i^{(N)} = \sum_{j=0}^{J_N} \beta^j \omega_N(\log x_i - 1 - j).$$  \hspace{1cm} (19)

This means that we actually employ two sieve approximations. The first truncates the infinite summation in (17) by means of $J_N$, whereas the second relates to the finite number of extra regimes $M_N$ in the neural network. The next result documents the conditions under which our semiparametric approach is consistent. The proof is straightforward, relying on the fact that (19) converges to the first term of the right-hand side of (17) as both $J_N$ and $M_N$ go to infinity with the sample size.

**Theorem 7.** If the duration process $x_i$ satisfies Definition 2, the sieve approximation error is negligible as long as $J_N \to \infty$ and $M_N^3 \log M_N = O(N)$.\hspace{1cm} (17)
To avoid overfitting, we take a regularization approach by penalizing the empirical loss function so as to control for the number of extra regimes $M_N$ (i.e., the number of hidden units in the neural-network approximation) as well as for the number of lags $J_N$ in the nonlinear AR representation. Let

$$
\mathcal{L}_N(\theta^{(N)}) = \frac{1}{N} \sum_{i=1}^{N} \ell_i^{(N)} (\theta^{(N)}) ,
$$

where

$$
\ell_i^{(N)} (\theta^{(N)}) = \psi_i^{(N)} \log \psi_i^{(N)} - \frac{X_i}{\psi_i^{(N)}} + \lambda_N \| \theta^{(N)} \| ,
$$

$\lambda_N$ is a regularization factor that shrinks to zero as the sample size increases. The sieve estimator then is

$$
\hat{\theta}^{(N)} = \arg\max_{\theta^{(N)} \in \Theta^{(N)}} \frac{1}{N} \sum_{i=1}^{N} \ell_i^{(N)} (\theta^{(N)}) .
$$

Given that $\mathcal{L} (\theta^{(N)}) = \mathbb{E} \left[ \ell_i^{(N)} (\theta^{(N)}) \right]$ is uniquely identified, the sieve estimator in (21) is well defined and hence Chen and Shen’s (1998) results hold.

6. REVISITING IBM PRICE DURATIONS

In this section, we estimate the FC-ACD model for the price durations of the IBM stock traded on the New York Stock Exchange (NYSE) from September to November 1996. In contrast to Zhang et al.’s (2001) empirical analysis of IBM durations, we do not fix the number of regimes in that we let the data determine the proper number of regimes using either a sequence of LM-type tests or a regularization approach in the parametric and semiparametric contexts, respectively. We define price duration as the time interval necessary to observe a cumulative change in the mid-price of at least $0.125. The main interest in models for price durations is due to the fact that they permit retrieving intraday estimates of the instantaneous volatility of the price process (Engle and Russell, 1998).

Apart from the opening auction, NYSE trading is continuous from 9:30 to 16:00. We remove all durations between events recorded outside the regular opening hours of
Figure 2. The first plot displays the time series of IBM price durations from September to November 1996, whereas the second plot exhibits its sample autocorrelation function up to 200 lags. The data correspond to diurnally adjusted durations \( x_i = D_i / \varphi(t_i) \), where \( D_i \) is the plain duration in seconds and \( \varphi(\cdot) \) denotes the diurnal factor determined by first averaging the durations over thirty minutes intervals for each day of the week and then fitting a cubic spline with nodes at each half hour.

The resulting (diurnally adjusted) durations serve as input for the remainder of the analysis.

A comparison between price and trade durations mirrors the fact that the IBM stock is very liquid. In particular, more than 75% of the trade durations do not exceed 30
seconds and it takes several transactions to alter the mid-quote price by at least $0.125. The sample size indeed reduces from 60,454 to 6,728 observations once we filter the data to compute price durations. Table 1 describes the main statistical properties of the IBM price durations. We compute descriptive statistics for both plain and diurnally adjusted data for two subsamples. We employ the first subsample with 4,484 observations for estimation purposes, reserving the second subsample with 2,244 observations for out-of-sample analysis.

The distributions of the price durations in the first and second subsamples are substantially different, regardless of the time-of-the-day adjustment. For instance, if one restricts attention to the diurnally adjusted series, the first-subsample mean, standard deviation, first quartile, and median are about twofold their counterparts in the second subsample. In addition, the third quartile declines by more than one half from the first to the second subsample, whereas the maximum value in the first subsample is three-fold the maximum in the second subsample. The minimum value and overdispersion are the only statistics that remain approximately constant across subsamples.

The evidence in favor of overdispersion is also robust to the time-of-the-day effect. The latter feature ensures that it is not an artifact due to data seasonality. Figure 2 displays the diurnally adjusted series of IBM price durations as well as its sample autocorrelation function up to 200 lags. It reveals that IBM price durations are very persistent in that there are significant positive values in the sample autocorrelation function at very high orders. Altogether, the combination of overdispersion and persistent autocorrelation in IBM price durations warrants the estimation of FC-ACD models with multiple regimes.

We then estimate by quasi-maximum likelihood the FC-ACD model of first order using the exponential distribution as reference. Table 2 reports the estimation and testing results for models with one and two regimes given that our modeling cycle strategy indicates that IBM price durations feature only two limiting regimes. The
Figure 3. The graph plots the logistic function in (5) against the sample values of the transition variable for \( c_1 = 0.3210 \) and \( \gamma = 496.99 \). The transition variable is the past value of the logarithm of the diurnally adjusted IBM price duration, whereas the sample consists of the first 4,484 observations from the period ranging from September to November 1996.

LM test for additional regimes indeed does not reject the null of only two limiting regimes at the usual levels of significance. Although the transition between the two regimes is very abrupt given the large value of \( \gamma \), Figure 3 shows that there are enough observations (i.e., about 200 data points) within the transition phase to estimate the parameters of the logistic function with reasonable precision.

The first regime is extremely persistent, with \( \hat{A}_0 = \hat{\alpha}_0 + \hat{\beta}_0 = 0.9909 \), whereas persistence subsides in the second regime given that \( \hat{A}_1 = \hat{\alpha}_0 + \hat{\alpha}_1 + \hat{\beta}_0 + \hat{\beta}_1 = 0.8696 \). The less persistent second regime mostly affects larger durations in view that \( \exp(\hat{c}_1) = 1.3784 \) lies slightly above the sample mean of the IBM price durations, at the 78% percentile. This is somewhat in line with the evidence put forth by Zhang et al. (2001), though they assume nonsmooth transitions between three fixed (rather than estimated) regimes in their threshold ACD model.
The plot displays the actual and fitted values of the IBM price durations from September to November 1996. Actual values are in gray, corresponding to diurnally adjusted IBM price durations. Fitted values are in black, relating to the estimates of the expected duration of the FC-ACD model with two regimes for the parameter values in Table 1. The dashed vertical line marks the sample splitting for estimation and forecasting purposes.

The results for the FC-ACD model with one regime, which corresponds to Bauwens and Giot’s (2000) logarithmic ACD model, show that ignoring the second regime affects substantially the analysis of persistence. The persistence of the one-regime model is a convex combination of the very distinct degrees of persistence that characterize the first and second regimes of the FC-ACD model. In particular, it is closer to the persistence in the first regime, which seems to prevail for 3,117 out of the 4,484 observations of the in-sample period. Allowing for the second regime not only entails a better picture of the persistent nature of IBM price durations, but also substantially improves both the in-sample and out-of-sample fits as measured by the quasi-likelihood function values.

Figure 4 displays the actual and fitted values of the IBM price duration for the full sample. Although the fitted values are not as volatile as the realizations of the IBM
price durations, it is evident that it tracks well the movements in the latter series. The in-sample and out-of-sample correlations between the actual and fitted log-values are quite reasonable, namely, 0.3832 and 0.3069, respectively. They add up to an overall correlation between actual and fitted log-values of 0.4391 in the full sample. Furthermore, the in-sample and out-of-sample residuals of the FC-ACD model with two regimes also have well-behaved distributions in that their mean and standard deviation are close to unity (as expected given the exponential benchmark). The in-sample residuals have a mean of 1.0001 with a standard deviation of 1.1536, whereas the mean and standard deviation of the out-of-sample residuals are 0.8949 and 1.0152, respectively. The overdispersion coefficients of the in-sample and out-of-sample residuals are respectively 1.1536 and 1.1344, and hence well below the overdispersion that we report in Table 1 for the IBM price durations.

To check for misspecification, we also inspect whether the in-sample and out-of-sample residuals display any serial correlation by looking at the sample autocorrelation function up to 200 lags. Table 2 documents that the FC-ACD model with two regimes does a much better job in accounting for the serial dependence in the IBM price durations than Bauwens and Giot’s (2000) logarithmic ACD model. The residual autocorrelation reduces by a palpable amount as one allows for the second regime. The decline is particularly strong for the in-sample residuals in that their maximum autocorrelation (in magnitude) for the one-regime model is about twofold the one of the FC-ACD model with two regimes.

7. CONCLUSION

This paper proposes a functional coefficient ACD model that accommodates overdispersion, intermittent dynamics, multiple regimes, as well as sign and size asymmetries in financial durations. In particular, we rely on a very flexible smooth-transition autoregressive specification with multiple regimes. The motivation lies on the fact that it gives way to a semiparametric version of the model as the number of regimes goes
to infinity. We formally address how to consistently estimate the parametric FC-ACD model with fixed number of regimes by quasi-maximum likelihood as well as the semi-parametric counterpart using a sieve approach.

An empirical illustration indicates that our functional coefficient specification is flexible enough to model IBM price durations in a congruent manner. This is in stark contrast with the alternative model with a single regime, whose residuals display much larger autocorrelations. In addition, we also evince that the FC-ACD model with two regimes outperforms the one-regime model in goodness-of-fit terms both in-sample and out-of-sample.
APPENDIX A. PROOFS

Proof of Theorem 1. We start by casting the FC-ACD process with multiple regimes into a smooth transition autoregressive moving average (STARMA) representation. Let \( \omega_{i-1} \equiv \omega(\log x_{i-1}) \), \( \alpha_{i-1} \equiv \alpha(\log x_{i-1}) \), and \( \beta_{i-1} \equiv \beta(\log x_{i-1}) \). It follows from (1) that the duration process has the following STARMA(1,1) representation:

\[
\log x_i = \omega_{i-1} + \left[ \alpha_{i-1} + \beta_{i-1} \right] \log x_{i-1} + \log \varepsilon_i - \beta_{i-1} \log \varepsilon_{i-1}. \tag{A.1}
\]

Following similar steps to Zhang et al. (2001), it is straightforward to show that the Markov chain in (6) is a \( \phi \)-irreducible \( \mathcal{T} \)-chain. This means that we may apply Tweedie’s (1975) drift criterion to derive sufficient conditions for strict stationarity and geometric ergodicity. In addition, Ling’s (1999) Theorem 4.1 implies that both strict stationarity and ergodicity of the functional coefficient ARMA model depends exclusively on its autoregressive part, and hence we confine attention to the analogous STAR(1) process with \( M + 1 \) regimes

\[
y_i = \tilde{v}_{i-1} + \tilde{\zeta}_{i-1} y_{i-1} + \zeta_i, \tag{A.2}
\]

where \( \tilde{v}_{i-1} \equiv v_0 + \sum_{m=1}^{M} v_m G_m(y_{i-1}), \tilde{\zeta}_{i-1} \equiv \zeta_0 + \sum_{m=1}^{M} \zeta_m G_m(y_{i-1}) \), and the error term \( \zeta_i \) is iid with \( \mathbb{E}[\zeta_i] < \infty \). The sufficient conditions for strict stationarity that we derive are exactly the same for TAR(1) processes (see, e.g., Chen and Tsay, 1991), though our derivation differs in view that (A.2) involves smooth transitions. For any \( e_C > 0 \), there exists a positive constant \( C > \max \{|\zeta|, |\tilde{\zeta}| \} \) such that \( |\tilde{\zeta}_{i-1} - \zeta_0| \leq e_C \) for any \( y_{i-1} < -C \) and \( |\tilde{\zeta}_{i-1} - \sum_{m=0}^{M} \zeta_m| \leq e_C \) for any \( y_{i-1} > C \). It then follows that

\[
y_i = \tilde{v}_{i-1} + \mathbf{1}_{\{y_{i-1} < -C\}} \tilde{\zeta}_{i-1} y_{i-1} + \mathbf{1}_{\{|y_{i-1}| \leq C\}} \tilde{\zeta}_{i-1} y_{i-1} + \mathbf{1}_{\{y_{i-1} > C\}} \tilde{\zeta}_{i-1} y_{i-1} + \zeta_i,
\]

where \( \mathbf{1}_{A} \) is the indicator function that takes value one if \( A \) is true and zero, otherwise. Taking absolute values of both sides gives way to

\[
|y_i| \leq L_C + \mathbf{1}_{\{y_{i-1} < -C\}} |\tilde{\zeta}_{i-1}| |y_{i-1}| + \mathbf{1}_{\{|y_{i-1}| \leq C\}} |\tilde{\zeta}_{i-1}| |y_{i-1}| + |\zeta_i|
\]

\[
\leq L_C + \tilde{\zeta}_{i-1}^+ |y_{i-1}| + |\zeta_i|
\]

\[
\leq |y_0| \sum_{j=0}^{i-1} \zeta_j^+ + \sum_{k=1}^{i-1} (|\zeta_k| + L_C) \prod_{j=k}^{i-1} \zeta_j^+ + |\zeta_i| + L_C,
\]

where \( \zeta_i^+ \equiv \mathbf{1}_{\{y_{i-1} < -C\}} (|\zeta_0| + e_C) + \mathbf{1}_{\{y_{i-1} > C\}} \left( \sum_{m=0}^{M} \zeta_m + e_C \right) \) and \( L_C \) is a positive constant that exceeds \( |\tilde{v}_{i-1}| + \mathbf{1}_{\{y_{i-1} < -C\}} |\tilde{\zeta}_{i-1}| C \). We then take conditional expectation yielding

\[
\mathbb{E}(\|y_i\| | y_0) \leq |y_0| \mathbb{E}(\prod_{j=0}^{i-1} \zeta_j^+ | y_0) + \sum_{k=1}^{i-1} \mathbb{E}(\|\zeta_k| + L_C) \prod_{j=k}^{i-1} \zeta_j^+ | y_0) + \mathbb{E}|\zeta_i| + L_C
\]

\[
= |y_0| \mathbb{E}(\prod_{j=0}^{i-1} \zeta_j^+ | y_0) + L_C^* \left[ 1 + \sum_{k=1}^{i-1} \mathbb{E}(\prod_{j=k}^{i-1} \zeta_j^+ | y_0) \right],
\]

25
where \( L_C^r \equiv \mathbb{E} |\zeta_1| + L_C \). We now have four cases to evaluate according to the signs of \( \zeta_0 \) and \( \zeta_* \equiv \sum_{m=0}^{M} \zeta_m \). In the first case, we consider \( \zeta_0 > 0 \) and \( \zeta_* > 0 \). It then holds that
\[
\mathbb{E} \left( |y_1| \mid y_0 \right) \leq |y_0| \mathbb{E} \left( \zeta_0^+ \mid y_0 \right) + L_C^r \\
\leq |y_0| \left[ \mathbf{1}_{(y_0 < -C)} \left( |\zeta_0| + e_C \right) + \mathbf{1}_{(y_0 > C)} \left( |\zeta_*| + e_C \right) \right] + L_C^r,
\]
and hence
\[
\mathbb{E} \left( |y_1| \mid y_0 < -C \right) \leq |y_0| \left( |\zeta_0| + e_C \right) + L_C.
\]
If \( 0 < \zeta_0 < 1 \), it is always possible to choose \( e_C < 1 - |\zeta_0| \), so that Tweedie’s (1975) drift criterion holds. Analogously,
\[
\mathbb{E} \left( |y_1| \mid y_0 > C \right) \leq |y_0| \left( |\zeta_*| + e_C \right) + L_C,
\]
and so the same result follows if \( 0 < \zeta_* < 1 \). In the second case, we assume that \( \zeta_0 < 0 \) and \( \zeta_* < 0 \). It then follows that
\[
\mathbb{E} \left( |y_2| \mid y_0 \right) \leq |y_0| \mathbb{E} \left( \zeta_0^+ \zeta_*^+ \mid y_0 \right) + L_C^r \left[ 1 + \mathbb{E} \left( \zeta_1^+ \mid y_0 \right) \right],
\]
where
\[
\mathbb{E} \left( \zeta_0^+ \zeta_*^+ \mid y_0 \right) = \mathbb{P} \left( y_1 < -C \mid y_0 < -C \right) \left( |\zeta_0| + e_C \right)^2 \\
+ \mathbb{P} \left( y_1 > C \mid y_0 < -C \right) \left( |\zeta_0| + e_C \right) \left( |\zeta_*| + e_C \right).
\]
However, for any \( a_C > 0 \), there exists some constant \( C \) that bounds from above the first term of the right-hand side of (A.3). This means that
\[
\mathbb{E} \left( \zeta_1^+ \zeta_*^+ \mid y_0 \right) \leq \left( |\zeta_0| + e_C \right) \left( |\zeta_*| + e_C \right) + a_C \\
= \zeta_0 \zeta_* + (|\zeta_0| + |\zeta_*|) e_C + e_C^2 + a_C
\]
satisfies Tjøstheim’s (1990) criterion (i.e., it does not exceed one) if \( \zeta_0 \zeta_* < 1 \) given that both \( e_C \) and \( a_C \) are arbitrarily small. As before, the same reasoning applies to the case in which \( y_0 > C \), yielding exactly the same condition. Finally, the third and fourth cases are symmetrical and hence we consider only the case of \( \zeta_0 < 0 \) and \( 0 < \zeta_* < 1 \). Letting \( h \equiv \inf_{j \in \mathbb{Z}_+} |\zeta_0 \zeta_*^{j-1}| < 1 \), observe that
\[
\mathbb{E} \left( |y_h| \mid y_0 \right) \leq |y_0| \mathbb{E} \left( \prod_{j=0}^{h-1} \zeta_j^+ \mid y_0 \right) + L_C^r \left[ 1 + \sum_{k=1}^{h-1} \mathbb{E} \left( \prod_{j=k}^{h-1} \zeta_j^+ \mid y_0 \right) \right].
\]
The argument \( \prod_{j=0}^{h-1} \zeta_j^+ \) will differ from zero only for the paths \( \{ \zeta_0^+, \ldots, \zeta_{h-1}^+ \} \) whose values are all greater than \( C \) in magnitude. To avoid a burdensome notation, we denote these paths by \( \mathcal{P}_j \), with \( j = 1, \ldots, 2^h \). It then ensues that
\[
\mathbb{E} \left( \prod_{j=0}^{h-1} \zeta_j^+ \mid y_0 \right) = \sum_{j=1}^{2^h} (|\zeta_0| + e_C)^{a_j} (|\zeta_*| + e_C)^{b_j} \mathbb{P} \left( \mathcal{P}_j \mid y_0 \right),
\]
where \( a_j = \sum_{k=1}^{h} \mathbf{1}_{(y_{h-k} < -C)} \) and \( b_j = \sum_{k=1}^{h} \mathbf{1}_{(y_{h-k} > C)} \). As before, it is straightforward to show that, for \( |y_0| > C \), the probability of \( \{ y_\ell < -C \} \) is arbitrarily small for any \( \ell = 1, \ldots, h-1 \) and Tjøstheim’s (1990) criterion depends exclusively on the values of \( (|\zeta_0| + e_C) \).
implies that \( (|ζ| + e_C) \). It indeed turns out that \[ \mathbb{E} \left( \prod_{j=0}^{k-1} ζ_j^+ \bigg| y_0 \right) < 1 \] for any \( 0 < ζ < 1 \) such that \( |ζ_0 ζ_0^{b-1}| < 1 \).

**Q.E.D.**

**Proof of Theorem 2.** The model given by (1)-(5) is continuous in the parameter vector \( \theta \) given that, for any value of \( \text{log} x_i \), the logistic function in (5) depends in a continuous manner on \( γ_m \) and \( c_m \). Similarly, the model is also continuous in \( \text{log} x_i \), and hence measurable for any fixed value of the parameter vector \( \theta \). The stationarity condition of Theorem 1 then ensures that \( \mathbb{E} \left[ \sup_{θ ∈ Θ} \log |ψ_{u,i}| \right] \) is finite, and thus \( \mathbb{E} |ψ_{u,i}(θ)| < ∞ \) for every \( θ ∈ Θ \).

**Q.E.D.**

**Proof of Theorem 3.** Let \( z_i = [1, \text{log} x_{i-1}, \text{log} ψ_{i-1}]' \), \( φ_j = [ω_j, α_j, β_j]' \) for \( j = 0, \ldots, M \) and \( ρ_m = (γ_m, c_m)' \) for \( m = 1, \ldots, M \). The parameter vector is \( \theta = [φ'_0, \ldots, φ'_M, ρ'_1, \ldots, ρ'_M]' \).

Consider now another parameter vector \( \tilde{θ} \equiv [\tilde{φ}'_0, \ldots, \tilde{φ}'_M, \tilde{ρ}'_1, \ldots, \tilde{ρ}'_M]' \) such that

\[
φ'_0 z_i + \sum_{m=1}^{M} φ'_m z_i \left( \text{log} x_{i-1}; ρ_m \right) = \tilde{φ}'_0 z_i + \sum_{m=1}^{M} \tilde{φ}'_m z_i \left( \text{log} x_{i-1}; \tilde{ρ}_m \right). \tag{A.4}
\]

To show global identifiability of the FC-ACD model, we must demonstrate that Assumption 4 ensures that (A.4) holds if and only if \( θ = \tilde{θ} \). It follows from (A.4) that

\[
φ'_0 z_i - \tilde{φ}'_0 z_i - \sum_{j=1}^{2M} φ'_j z_i \left( \text{log} x_{i-1}; ρ_j \right) = 0, \tag{A.5}
\]

where \( \tilde{φ}_j = φ_j \) for \( j = 1, \ldots, M \), \( \tilde{ρ}_j = \tilde{ρ}_{j-M} \) for \( j = M + 1, \ldots, 2M \), \( \tilde{φ}_j = φ_j \) for \( j = 1, \ldots, M \), and \( \tilde{φ}_j = φ_{j-M} \) for \( j = M + 1, \ldots, 2M \). For the sake of notation simplicity, let \( ψ_{x_{i-1}} = ψ \left( \text{log} x_{i-1}; ρ_j \right) \) for \( j = 1, \ldots, 2M \). Hwang and Ding’s (1997) Lemma 2.7 implies that, if \( ϕ_{j_1} \) and \( ϕ_{j_2} \) are not sign-equivalent for \( j_1 ∈ \{1, \ldots, 2M\} \) and \( j_2 ∈ \{1, \ldots, 2M\} \), (A.5) holds if and only if \( φ_0, \tilde{φ}_0, \) and \( φ_j \) jointly vanish for every \( j ∈ \{1, \ldots, 2M\} \). Conditions C2 and C3 in Assumption 4 however preclude that possibility because they guarantee that there are no irrelevant limiting regimes. Although this means that \( ϕ_{j_1} \) and \( ϕ_{j_2} \) must be sign-equivalent, they must also come from different models; otherwise it would contradict C2 in Assumption 4. There thus exist \( j_1 ∈ \{0, \ldots, M\} \) and \( j_2 ∈ \{M + 1, \ldots, 2M\} \) such that \( ϕ_{j_1} \) and \( ϕ_{j_2} \) are sign-equivalent. Assumption 4 implies that (A.4) holds only if \( φ_m = φ_m = \tilde{φ}_m \), \( m = 1, \ldots, M \) given that C1 rules out the permutation of regimes. It now remains to show that \( \theta_0 \) uniquely maximizes the log-likelihood function \( L(θ) \). Letting \( ψ_i(θ_0) = x_i/ε_i(θ_0) \) denote the true conditional duration process, one may rewrite, as in Lumsdaine (1996), the maximization problem as

\[
\max_{θ ∈ Θ} \left( L(θ) - L(θ_0) \right) = \max_{θ ∈ Θ} \mathbb{E} \left[ \text{log} \frac{ψ_i(θ_0)}{ψ_{u,i}} - \frac{ψ_i(θ_0)}{ψ_{u,i}} - 1 \right].
\]
In addition, for any \( y > 0 \), \( m(y) = y - \log(y) \leq 0 \), so that
\[
E \left[ \log \frac{\psi_i(\theta_0)}{\psi_{u,i}} \right] \leq 0.
\]
Given that \( m(y) \) achieves its maximum at \( y = 1 \), \( E[m(y)] \leq E[m(1)] \) with equality holding almost surely only if \( \log \psi_i(\theta_0) \) and \( \log \psi_{u,i} \) coincide with probability one. By the mean value theorem, this is equivalent to showing that
\[
(\theta - \theta_0) \frac{\partial \log \psi_{u,i}}{\partial \theta} = 0
\]
with probability one. A straightforward application of Lemma 1 then shows that this happens if and only if \( \theta = \theta_0 \), completing the proof.

**Proof of Theorem 4.** To show that \( \widehat{\theta}_{u,N} \) converges in probability to \( \theta_0 \), it suffices to verify whether Newey and McFadden’s (1994) regularity conditions hold under Assumptions 1 to 4. Assumption 3 takes care of their first condition, which relates to the compactness of the parameter space. Theorems 2 and 3 ensure the validity of their second and third conditions, which require the log-likelihood function to be continuous in the parameter vector \( \theta \), with a unique maximum at \( \theta_0 \), and measurable with respect to the duration process \( \{x_i, \ i \in \mathbb{N}\} \) for all \( \theta \in \Theta \). Finally, Lemma 2 fulfills the requirements of their last condition, i.e., \( \mathcal{L}_{u,N}(\theta) \xrightarrow{P} \mathcal{L}(\theta) \). This means that \( \widehat{\theta}_{u,N} \xrightarrow{P} \theta_0 \), so that it now remains to demonstrate that \( \| \widehat{\theta}_N - \widehat{\theta}_{u,N} \| \xrightarrow{P} 0 \). We do that in Lemma 3 by showing that \( \sup_{\theta \in \Theta} |\mathcal{L}_{u,N}(\theta) - \mathcal{L}_N(\theta)| \xrightarrow{P} 0 \), and hence \( \widehat{\theta}_N \xrightarrow{P} \theta_0 \).

**Q.E.D.**

**Proof of Theorem 5.** As before, we first tackle the asymptotic normality of the QML estimator that hinges on the unobserved log-likelihood function \( \mathcal{L}_{u,N}(\theta) \) and then employ Lemmas 3 and 5 to extend the result for the QML estimator based on the observed log-likelihood function \( \mathcal{L}_N(\theta) \). Asymptotic normality of the QML estimator requires four additional regularity conditions. First, the true parameter vector \( \theta_0 \) must lie in the interior of the parameter space \( \Theta \). Second, the matrix
\[
A_N(\theta) = \frac{1}{N} \sum_{i=1}^{N} \left( \frac{\partial^2 \ell_i(\theta)}{\partial \theta \partial \theta'} \right)
\]
exists and is continuous in \( \Theta \). Third, the matrix \( A_N(\theta) \xrightarrow{P} A_0 \) for any sequence \( \theta_N \) such that \( \theta_N \xrightarrow{P} \theta_0 \). Fourth, the score vector satisfies
\[
\frac{1}{N} \sum_{i=1}^{N} \left( \frac{\partial \ell_i(\theta)}{\partial \theta} \right) \xrightarrow{d} N(0, B_0).
\]
We next verify these conditions. Assumption 3 ensures that the first condition holds, whereas Lemma 5 substantiates the third condition. The second condition follows from the stationarity of the FC-ACD model and from the fact that \( \ell_i(\theta) \) is twice differentiable on \( \theta \in \Theta \). In fact, \( A_0 \)
and $B_0$ are nonsingular due to the model identifiability (see Hwang and Ding, 1997). Finally, Lemma 4 shows that the score condition also holds, completing the proof.

Q.E.D.

**Proof of Theorem 6.** The local approximation to the instantaneous quasi-log-likelihood function in a neighborhood of $H_0$ is $\ell_i(\theta) = -\log \psi_i(\theta) - x_i/\psi_i(\theta)$. Let $\theta = [\theta_1', \theta_2']'$ with

$$
\theta_1 = (\bar{\omega}_0, \omega_1, \ldots, \omega_{M-1}, \bar{d}_0, \alpha_1, \ldots, \alpha_{M-1}, \bar{\beta}_0, \beta_1, \ldots, \beta_{M-1}, c_1, \ldots, c_{M-1}, \gamma_1, \ldots, \gamma_{M-1})',
$$

and $\theta_2 = (\delta_1, \delta_2)'$. The resulting score vector thus is

$$
q(\theta) = (q(\theta_1)', q(\theta_2)')' = \sum_{i=1}^N \left( \frac{\partial}{\partial \theta_1} \ell_i(\theta) \right) = \sum_{i=1}^N \left( \frac{x_i}{\psi_i} - 1 \right) \left( v_i \overline{u}_i \right)
$$

with $v_i = \partial \log \psi_i(\theta)/\partial \theta_1$ and $u_i = \partial \log \psi_i(\theta)/\partial \theta_2$, whereas the information matrix reads

$$
A(\theta) = \mathbb{E} \left[ -\frac{\partial^2 \ell_i(\theta)}{\partial \theta \partial \theta} \right] = \mathbb{E} \left[ \frac{1}{\psi_i^2} \frac{\partial \psi_i}{\partial \theta} \frac{x_i}{\psi_i} \right. \left. \left( \frac{x_i}{\psi_i} - 1 \right) \frac{\partial}{\partial \theta} \left( \frac{1}{\psi_i} \frac{\partial \psi_i}{\partial \theta} \right) \right]
$$

$$
= \mathbb{E} \left[ \frac{1}{\psi_i^2} \frac{\partial \psi_i}{\partial \theta} \frac{x_i}{\psi_i} \right] \mathbb{E} \left[ v_i v_i' \overline{u}_i \overline{u}_i' \right].
$$

Consider next the consistent estimator for the information matrix $A(\theta)$ given by

$$
A_N(\theta) = \frac{1}{2N} \sum_{i=1}^N \left( v_i v_i' \overline{u}_i \overline{u}_i' \right)
$$

and let $d_i = (v_i', u_i')'$. As in Godfrey (1988, page 16), the $LM$ statistic thus is

$$
LM = q(\theta)|_{\theta_0} \left[ A_N(\theta)|_{\theta_0} \right]^{-1} q(\theta)|_{\theta_0}
$$

$$
= N \left[ \sum_{i=1}^N \left( \frac{x_i}{\psi_i} - 1 \right) d_i \right] \left( \sum_{i=1}^N \overline{d}_i \overline{d}_i' \right)^{-1} \left[ \sum_{i=1}^N \left( \frac{x_i}{\psi_i} - 1 \right) d_i \right].
$$

To complete the proof, it then suffices to apply Lemmas 4 and 5.

Q.E.D.

**Proof of Theorem 7.** The approximation error consists of

$$
\log \psi_i^{(N)} - \log \psi_i = \sum_{j=0}^{\infty} \left( \beta_N^{J \omega_{Nj}} - \beta_0^{J \omega_{0j}} \right) - \sum_{j=J_N+1}^{\infty} \beta_N^{J \omega_{Nj}}
$$

$$
= \sum_{j=0}^{\infty} \beta_0^{J} \left( \omega_{Nj} - \omega_{0j} \right) + \sum_{j=0}^{J_N} \left( \beta_0^{J} - \beta_0^{J} \right) \omega_{Nj} - \sum_{j=J_N+1}^{\infty} \beta_N^{J} \omega_{Nj},
$$

where $\omega_{0j} = \omega_0(\log x_{i-1-j})$ and $\omega_{Nj} = \omega_N(\log x_{i-1-j})$. There are two approximation errors. The first is due to the finite number of regimes in the neural network (i.e., first two terms), whereas the second stems from the lag truncation (i.e., third term). Lemma 6 shows that the latter is at most of order $O_p \left( \beta^{J_N} \right)$. As for the former, Chen and Shen’s (1998) Proposition 1 ensures that it is at most of order $O_p \left( \left[ N/ \log N \right]^{-1/3} \right)$ provided that $M_N^3 \log M_N = O(N)$. 

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We must then show that Chen and Shen’s (1998) Conditions A.1 to A.4 hold within the semi-parametric FC-ACD context. Definition 2 ensures geometric ergodicity given that $|\beta_0| < 1$, thereby satisfying Condition A.1, whereas Condition A.3 ensues exactly as in their proof of the Case 1.1 of Proposition 1. It remains to show that Conditions A.2 and A.4 are also valid. The former requires that

$$
\sup_{\|\theta_N - \theta_0\| \leq \delta_1} \forall (\ell_{\theta_N i} - \ell_{\theta_0 i}) \leq O(\delta_1^2)
$$

for all small $\delta_1 > 0$, whereas the latter necessitates that, for any $\delta_2 > 0$, there exists $0 < s < 2$ and a measurable function $U_N(\cdot)$ such that

$$
\sup_{\|\theta_N - \theta_0\| \leq \delta_1} |\ell_{\theta_N i} - \ell_{\theta_0 i}| \leq \delta_2^s U_N(\log x_i)
$$

with $\sup_N \mathbb{E} \left[ U_N^s(\log x_i) \right] \leq O(1)$ for $s > 2$. Letting $\theta_N \equiv \sum_{i=1}^{\infty} \beta_N \omega_N(\log x_{i-j-1})$, $\theta_0 \equiv \sum_{i=1}^{\infty} \beta_0 \omega_0(\log x_{i-j-1})$, $e_i(\theta_N) = \log e_i(\theta_N)$ and $e_i(\theta_0) = \log e_i(\theta_0)$, yields

$$
\ell_{\theta_N i} - \ell_{\theta_0 i} = - \frac{1}{2} (e_i(\theta_N) - e_i(\theta_0)) - \frac{1}{2} [e_i(\theta_N) + e_i(\theta_0)] [e_i(\theta_N) - e_i(\theta_0)] = (\theta_N - \theta_0) \left( e_i(\theta_0) - \frac{\theta_N - \theta_0}{2} \right).
$$

Condition A.4 then holds for $s = 2/3$ and $U_N(\log x_i) = |e_i(\theta_0)| + c_N$, with $c_N \to \infty$ arbitrarily slowly, given that $\|\theta_N\| \leq c$ for every $\theta_N$ in the sieves parameter space and

$$
|\ell_{\theta_N i} - \ell_{\theta_0 i}| \leq \|\theta_N - \theta_0\|_{\sup} \left[ e_i(\theta_0) + \frac{\|\theta_N\|_{\sup} + \|\theta_0\|_{\sup}}{2} \right].
$$

(Note the implicit use of Chen and Shen’s (1998) Lemma 2 to change from the sup norm to the $L^2$ norm.) It now remains to bound the variance of $\ell_{\theta_N i} - \ell_{\theta_0 i}$. The first moment is

$$
\mathbb{E} [\ell_{\theta_N i} - \ell_{\theta_0 i}] = \mathbb{E} \left[ (\theta_N - \theta_0) \left( e_i(\theta_0) - \frac{\theta_N - \theta_0}{2} \right) \right] = - \frac{1}{2} \mathbb{E}(\theta_N - \theta_0)^2,
$$

whereas the second moment reads

$$
\mathbb{E} [\ell_{\theta_N i} - \ell_{\theta_0 i}]^2 = \mathbb{E} (\theta_N - \theta_0)^2 \mathbb{E} [e_i^2(\theta_0)] + \frac{1}{4} \mathbb{E} (\theta_N - \theta_0)^4 = \sigma^2 \mathbb{E} (\theta_N - \theta_0)^2 + \frac{1}{4} \mathbb{E} (\theta_N - \theta_0)^4 \leq \left\{ \sigma^2 + \mathbb{E} \sup_{\|\theta_N - \theta_0\| \leq \delta_1} (\theta_N - \theta_0)^2 \right\} \mathbb{E} (\theta_N - \theta_0)^2.
$$

Altogether, this means that the variance is at most of order $O(\delta_1^2)$ as in Condition A.2 of Chen and Shen (1998).

Q.E.D.
APPENDIX B. LEMMAS

LEMMA 1. Suppose that $x_i$ follows a FC-ACD process with $M + 1$ regimes given by (1)–(5) that satisfies Assumptions 1 to 4. Let $d$ be a constant vector with the same dimension as $\theta$. It then follows that

$$d' \left( \frac{\partial \log \psi_{u,i}}{\partial \theta} \right) = 0 \quad \text{a.s.}$$

if and only if $d = 0$.

PROOF. We follow the same reasoning as in the proof of Lumsdaine’s (1996) Lemma 5. Define $\xi_i \equiv \partial \log \psi_i / \partial \theta$ and $G_{m,i} \equiv G(\log x_i; \gamma_m, c_m)$. It is straightforward to show that

$$\xi_i = \beta (\log x_{i-1}) \xi_{i-1} + \kappa_{i-1},$$

where

$$\kappa_{i-1} = \begin{bmatrix}
1, \log x_{i-1}, \log \psi_{i-1}, G_{1,i-1}, \ldots, G_{M,i-1}, \\
G_{1,i-1} \log x_{i-1}, \ldots, G_{M,i-1} \log x_{i-1}, G_{1,i-1} \log \psi_{i-1}, \ldots, G_{M,i-1} \log \psi_{i-1}, \\
(\omega_1 + \alpha_1 \log x_{i-1} + \beta_1 \log \psi_{i-1}) \frac{\partial G_{1,i-1}}{\partial \gamma_1}, \ldots, \\
(\omega_M + \alpha_M \log x_{i-1} + \beta_M \log \psi_{i-1}) \frac{\partial G_{M,i-1}}{\partial \gamma_M}, \\
(\omega_1 + \alpha_1 \log x_{i-1} + \beta_1 \log \psi_{i-1}) \frac{\partial G_{1,i-1}}{\partial c_1}, \ldots, \\
(\omega_M + \alpha_M \log x_{i-1} + \beta_M \log \psi_{i-1}) \frac{\partial G_{M,i-1}}{\partial c_M}
\end{bmatrix}',$$

so that $d' \xi_i = d' \beta (\log x_{i-1}) \xi_{i-1} + d' \kappa_{i-1}$. It then follows by assumption that $d' \xi_i = 0$ and $d' \xi_{i-1} = 0$ with probability one, implying that $d' \kappa_{i-1} = 0$ with probability one. In view that $\kappa_i$ is nondegenerate, $d' \xi_i = 0$ with probability one if and only if $d = 0$.

Q.E.D.

LEMMA 2. If $x_i$ follows a FC-ACD process with $M + 1$ regimes given by (1)–(5) that satisfies Assumptions 1 to 4, then $\sup_{\theta \in \Theta} |L_{u,N}(\theta) - L(\theta)| \overset{p}{\to} 0$.

PROOF. We derive this result by building on the proof of Lemma 4.3 in Ling and McAleer (2003). Let $g(X_t, \theta) = \ell_{u,i}(\theta) - \mathbb{E} [\ell_{u,i}(\theta)]$, where $X_i = (x_i, x_{i-1}, x_{i-2}, \ldots)'$. Theorem 2 implies that $\mathbb{E} \left[ \sup_{\theta \in \Theta} |g(X_t, \theta)| \right] < \infty$. The result then ensues from the fact that Theorem 3.1 in Ling and McAleer (2003) implies that $\sup_{\theta \in \Theta} \left| N^{-1} \sum_{t=1}^{N} g(X_t, \theta) \right| = o_p(1)$ in view that $g(X_t, \theta)$ is stationary with zero mean.

Q.E.D.
LEMMA 3. If \( x_i \) follows a FC-ACD process with \( M + 1 \) regimes given by (1)-(5) that satisfies Assumptions 1 to 4, then \( \sup_{\theta \in \Theta} |L_{u,N}(\theta) - L_N(\theta)| \overset{p}{\rightarrow} 0. \)

PROOF. We follow the proof of the first result in Lumsdaine’s (1996) Lemma 6. The conditions in Theorem 1 ensure that \( \log \psi_{u,0} \) is well defined and that, as the constant \( k \rightarrow \infty, \)

\[
\Pr\left( \sup_{\theta \in \Theta} (\log \psi_{u,0}) > k \right) \rightarrow 0.
\]

Combining (7) and (9) gives way to

\[
\log \psi_{u,i} - \log \psi_i = (\log \psi_{u,0} - \log \psi_0) \prod_{j=1}^i \beta(\log x_j).
\]

Defining two finite positive constants \( \delta \) and \( \bar{\delta} \) such that \( \log \psi_i > \delta \) and \( \beta(\log x_i) \leq \bar{\delta} \) then leads to

\[
0 \leq \left| N^{-1/2} \sum_{i=1}^N \log \left( \frac{\psi_{u,i}}{\psi_i} \right) \right|^p \leq \left[ N^{-1/2} \sum_{i=1}^N \log \left( \frac{\psi_{u,i}}{\psi_i} \right) \right]^p
\]

\[
= \left[ N^{-1/2} \sum_{i=1}^N \log \left( \frac{\psi_{u,0}}{\psi_i} \right) \prod_{j=1}^i \beta(\log x_j) \right]^p
\]

\[
\leq N^{-p/2} \left[ \log \left( \frac{\psi_{u,0}}{\delta} \right) \right]^p \left[ \sum_{i=1}^N \prod_{j=1}^i \beta(\log x_j) \right]^p.
\]

The upper bound of the latter expression converges in probability uniformly to zero by Theorem 1 and Slutsky’s Theorem, and hence

\[
\Pr\left( \sup_{\theta \in \Theta} \sum_{i=1}^N |\log \psi_{u,i} - \log \psi_i| > k \right) \rightarrow 0
\]

as the sample size grows for any constant \( k > 0 \). It remains to show that

\[
\sup_{\theta \in \Theta} \left| N^{-1/2} \sum_{i=1}^N \left( \frac{x_i}{\psi_{u,i}} - \frac{x_i}{\psi_i} \right) \right|^p \overset{p}{\rightarrow} 0.
\]

To that end, we first observe that

\[
\left[ N^{-1/2} \sum_{i=1}^N x_i \left( \frac{\psi_i - \psi_{u,i}}{\psi_{u,i} \psi_i} \right) \right]^p \leq \frac{1}{N^{p/2} \delta^{2p}} \left[ \sum_{i=1}^N x_i \left( \psi_i - \psi_{u,i} \right) \right]^p
\]

\[
= \frac{1}{N^{p/2} \delta^{2p}} \left[ \sum_{i=1}^N x_i^2 \left( \psi_0 - \psi_{u,0} \right) \prod_{j=1}^i \beta(\log x_j) \right]^p.
\]

Define \( \xi_i \equiv \left| (\psi_0 - \psi_{u,0}) \prod_{j=1}^i \beta(\log x_j) \right| \). Under the conditions of Theorem 1, the duration process is a strictly stationary and ergodic with \( \mathbb{E}|x_i| < \infty \). In addition, it holds that
sup \( 1 \leq i \leq N \) \( |\xi_i| \leq C_N \), where \( C_N \) is some finite constant, and \( \frac{1}{N} \sum_{i=1}^{N} |\xi_i| = o_p(1) \). To conclude the proof, it now suffices to apply Ling and McAleer’s (2003) Lemma 4.5 to show that \( N^{-1} \sum_{i=1}^{N} x_i \xi_i = o_p(1) \), and hence

\[
\frac{1}{N^{p/2}} \left[ \sum_{i=1}^{N} x_i \left( \psi_0 - \psi_{u,0} \right) \prod_{j=1}^{i} \beta(\log x_j) \right]^{p} \xrightarrow{p} 0.
\]

Q.E.D.

**Lemma 4.** The conditions of Theorem 5 ensure not only that \( \mathbb{E} \left[ \frac{\partial}{\partial \theta} \ell_i(\theta) \big|_{\theta=\theta_0} \right] \) exists and is finite, but also that \( B_0 \) is finite and positive definite, and that

\[
\frac{1}{\sqrt{N}} \sum_{i=1}^{N} \frac{\partial \ell_i(\theta)}{\partial \theta} \bigg|_{\theta=\theta_0} \xrightarrow{d} N(0, B_0).
\]

**Proof.** The existence of \( \mathbb{E} \left[ \frac{\partial}{\partial \theta} \ell_i(\theta) \big|_{\theta=\theta_0} \right] < \infty \) immediately follows from the conditions of Theorem 1. Letting then

\[
\nabla_0 \ell_{u,i} = \frac{\partial \ell_{u,i}(\theta)}{\partial \theta} \bigg|_{\theta=\theta_0} \quad \text{and} \quad \nabla_0 \log \psi_{u,i} = \frac{\partial \log \psi_{u,i}}{\partial \theta} \bigg|_{\theta=\theta_0}
\]

yields

\[
\nabla_0 \ell_{u,i} \nabla_0 \ell_{u,i} = (e_1^2 - 2e_1 + 1) \nabla_0 \log \psi_{u,i} \nabla_0 \log \psi_{u,i}.
\]

Let \( \delta < \infty \) be a positive constant such that \( \log \psi_{u,i} > \delta \). Under the strict stationarity condition of Theorem 1, we may employ the same reasoning as in the proof of Lemma 1 in Boussama (2000), giving way to

\[
\mathbb{E} \left[ \nabla_0 \log \psi_{u,i} \nabla_0 \log \psi_{u,i}' \right] < K_1,
\]

where \( K_1 \) is a constant matrix with finite elements, and

\[
\mathbb{E} \left[ \nabla_0 \ell_{u,i} \nabla_0 \ell_{u,i}' \right] \leq K_1 \mathbb{E} (e_1^2 - 2e_1 + 1) = K_1 (\mu_2 - 1),
\]

which is finite given that \( \mu_2 \equiv \mathbb{E} (e_1^2) < \infty \). This means that \( B_0 \) is finite. The conditions of Theorems 1 and 3 also ensure that \( B_0 \) is positive definite. It now remains to show the asymptotic normality of the score vector. Let \( S_N = \sum_{i=1}^{N} k' \nabla_0 \ell_{u,i} \), where \( k \) is a constant vector. It then follows that \( S_N \) is a martingale with respect to the filtration \( \mathcal{F}_i \) with a positive expected value, and hence

\[
N^{-1/2} S_N \xrightarrow{d} \mathcal{N} (0, k'B_0k)
\]

by Stout’s (1974) central limit theorem. A straightforward application of the Cramér-Wold device then yields

\[
N^{-1/2} \sum_{i=1}^{N} \frac{\partial \ell_{u,i}(\theta)}{\partial \theta} \bigg|_{\theta=\theta_0} \xrightarrow{d} \mathcal{N} (0, B_0),
\]

whereas it is also possible to show, as in the proof of Lemma 3, that

\[
N^{-1/2} \sum_{i=1}^{N} \left| \frac{\partial \ell_{u,i}(\theta)}{\partial \theta} \bigg|_{\theta=\theta_0} - \frac{\partial \ell_i(\theta)}{\partial \theta} \bigg|_{\theta=\theta_0} \right| \xrightarrow{p} 0.
\]
We thus conclude that
\[ N^{-1/2} \sum_{i=1}^{N} \left. \frac{\partial \ell_i(\theta)}{\partial \theta} \right|_{\theta=\theta_0} \overset{d}{\to} \mathcal{N}(0, \mathbf{B}_0), \]
completing the proof.

Q.E.D.

**Lemma 5.** Under the conditions of Theorem 5, both
\[ \sup_{\theta \in \Theta} \left| \frac{1}{N} \sum_{i=1}^{N} \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} - \mathbb{E} \left[ \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} \right] \right| \quad \text{and} \quad \sup_{\theta \in \Theta} \left| \frac{1}{N} \sum_{i=1}^{N} \left[ \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} - \frac{\partial^2 \ell_i(\theta)}{\partial \theta \partial \theta'} \right] \right| \]
converge in probability to zero.

**Proof.** If we define
\[ \nabla_0^2 \ell_{u,i} = \left. \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} \right|_{\theta=\theta_0} \quad \text{and} \quad \nabla_0^2 \log \psi_{u,i} = \left. \frac{\partial^2 \log \psi_{u,i}}{\partial \theta \partial \theta'} \right|_{\theta=\theta_0}, \]
then
\[ \nabla_0^2 \ell_{u,i} = \left( \frac{x_i}{\psi_{u,i}} - 1 \right) \nabla_0^2 \log \psi_{u,i} - \left( \frac{x_i}{\psi_{u,i}} \right) \nabla_0 \log \psi_{u,i} \nabla_0 \log \psi_{u,i}. \]
Because \( \nabla_0^2 \log \psi_{u,i} \) consists exclusively of second-order terms, it ensues from the conditions of Theorem 1 that \( \mathbb{E} \left[ \nabla_0^2 \log \psi_{u,i} \right] \leq \mathbf{K}_2 \), where \( \mathbf{K}_2 \) is a constant matrix with finite elements. This implies that
\[ \nabla_0^2 \ell_{u,i} \leq (\epsilon_i - 1) \mathbf{K}_2 - \epsilon_i \mathbf{K}_1, \]
so that \( \mathbb{E} \left[ \nabla_0^2 \ell_{u,i} \right] \) is finite. By Theorem 3.1 in Ling and McAleer (2003),
\[ \sup_{\theta \in \Theta} \left| \frac{1}{N} \sum_{i=1}^{N} \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} - \mathbb{E} \left[ \frac{\partial^2 \ell_{u,i}(\theta)}{\partial \theta \partial \theta'} \right] \right| \overset{p}{\to} 0. \]
We omit the proof of the second result given that it very much resembles the proof of Lemma 3.

Q.E.D.

**Lemma 6.** If the semiparametric FC-ACD process is stationary with finite second moments and \( \beta \)-mixing with exponential decay, the approximation error due to the lag truncation is negligible in that
\[ \sum_{j=J_N+1}^{\infty} \beta_0^j \bar{\omega}_{N_j} \leq O_p \left( \beta_0^{J_N} \right). \]

**Proof.** We first show that both the expectation and variance of the left-hand side of (B.6) converge to zero as the sample size increases and then complete the proof applying Chebyshev’s inequality. Stationarity implies that
\[ \mathbb{E} \left( \sum_{j=J_N+1}^{\infty} \beta_0^j \bar{\omega}_{N_j} \right) = \mathbb{E} \left( \bar{\omega}_{N_1} \right) \sum_{j=J_N+1}^{\infty} \beta_0^j = \mathbb{E} \left( \bar{\omega}_{N_1} \right) \frac{\beta_0^{J_N+1}}{1-\beta_0}. \]
and that
\[ V \left( \sum_{j=J_N+1}^{\infty} \beta_0^j \bar{\omega}_{Nj} \right) = \sum_{j=J_N+1}^{\infty} \beta_0^{2j} V (\bar{\omega}_{Nj}) + 2 \sum_{J_N+1 \leq j < k < \infty} \beta_0^{j+k} \text{Cov} (\bar{\omega}_{Nj}, \bar{\omega}_{Nk}). \]

The first term of the right-hand side is of order \( O \left( \beta_0^{2J_N} \right) \). As for the second term, we take benefit from the fact that the semiparametric FC-ACD process is, by assumption, \( \beta \)-mixing with exponential decay to employ the covariance inequality in Dette and Spreckelsen’s (2004) Lemma A1: for some \( \delta > 0 \),

\[ |\text{Cov}(\bar{\omega}_{Nj}, \bar{\omega}_{Nk})| \leq 4 \left[ \mathbb{E} |\bar{\omega}_{N1}\rangle^{1+\delta} \right]^{\frac{1}{1+\delta}} \rho_{k-j}^\delta, \quad 1 \leq j < k \]

where \( \rho_j \) is the mixing coefficient (see also Lemma 1 in Yoshihara, 1976). In particular, exponential decay means that the latter is of order \( O(\eta^j) \) with \( 0 < \eta < 1 \) and so

\[
\left| \sum_{J_N+1 \leq j < k < \infty} \beta_0^{j+k} \text{Cov}(\bar{\omega}_{Nj}, \bar{\omega}_{Nk}) \right| \leq 4 \left[ \mathbb{E} |\bar{\omega}_{N1}\rangle^{1+\delta} \right]^{\frac{1}{1+\delta}} \sum_{J_N+1 \leq j < k < \infty} \beta_0^{j+k} O \left( \eta^{\frac{j}{1+\delta}} (k-j) \right) \\
= 4 \left[ \mathbb{E} |\bar{\omega}_{N1}\rangle^{1+\delta} \right]^{\frac{1}{1+\delta}} \sum_{j=J_N+1}^{\infty} \beta_0^j O \left( \eta^{\frac{j}{1+\delta}} \right) \sum_{k=j+1}^{\infty} \beta_0^k O \left( \eta^{\frac{k}{1+\delta}} \right) \\
= 4 \left[ \mathbb{E} |\bar{\omega}_{N1}\rangle^{1+\delta} \right]^{\frac{1}{1+\delta}} \sum_{j=J_N+1}^{\infty} \beta_0^j O \left( \eta^{\frac{j}{1+\delta}} \right) \frac{\beta_0^{j+1} O \left( \eta^{\frac{j+1}{1+\delta}} \right)}{1 - \beta O \left( \eta^{\frac{j+1}{1+\delta}} \right)} \\
= 4 \left[ \mathbb{E} |\bar{\omega}_{N1}\rangle^{1+\delta} \right]^{\frac{1}{1+\delta}} \sum_{j=J_N+1}^{\infty} \beta_0^{2j+1} O \left( \eta^{\frac{j}{1+\delta}} \right) \left[ 1 - \beta O \left( \eta^{\frac{j}{1+\delta}} \right) \right]^{-1} \sum_{j=J_N+1}^{\infty} \beta_0^{2j+1} \\
= 4 \left[ \mathbb{E} |\bar{\omega}_{N1}\rangle^{1+\delta} \right]^{\frac{1}{1+\delta}} O \left( \eta^{\frac{1}{1+\delta}} \right) \left[ 1 - \beta O \left( \eta^{\frac{1}{1+\delta}} \right) \right]^{-1} \beta_0^{2J_N+3} \frac{1 - \beta_0^2}{1 - \beta_0^2} = O \left( \beta_0^{2J_N} \right). 
\]

This means that the expectation and standard deviation of (B.6) are both at most of order \( O \left( \beta_0^{J_N} \right) \), and hence the approximation error due to the lag truncation is at most of order \( O_p \left( \beta_0^{J_N} \right) \) by Chebyshev’s inequality.

\( Q.E.D. \)
References


Lumsdaine, R., 1996, Consistency and asymptotic normality of the quasi-maximum likelihood estimator in IGARCH(1,1) and covariance stationary GARCH(1,1) models, Econometrica 64, 575–596.


Sussman, H. J., 1992, Uniqueness of the weights for minimal feedforward nets with a given input-output map, Neural Networks 5, 589–593.


Table 1
Descriptive statistics of IBM price durations

Price durations refer to the time interval necessary to observe a cumulative change in the mid-price of at least $0.125. We document the descriptive statistics for both plain and diurnally adjusted durations for the period running from September to November 1996. The latter corresponds to $x_i = D_i/\varphi(t_i)$, where $D_i$ is the plain duration in seconds and $\varphi(\cdot)$ denotes the diurnal factor as measured by first averaging the durations over thirty minutes intervals for each day of the week and then fitting a cubic spline with nodes at each half hour. The in-sample period considers the first 4,484 observations of the data set, whereas the remaining 2,244 observations compose the out-of-sample period.

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Table 2
Estimation results for IBM price durations

Price durations refer to the time interval necessary to observe a cumulative change in the mid-price of at least \$0.125. The data are diurnally adjusted durations from September to November 1996, namely, $x_i = D_i / \varphi(t_i)$, where $D_i$ is the plain duration in seconds and $\varphi(\cdot)$ denotes the diurnal factor as measured by first averaging the durations over thirty minutes intervals for each day of the week and then fitting a cubic spline with nodes at each half hour. We then estimate by quasi-maximum likelihood the FC-ACD model with two regimes for the first 4,484 observations of the sample. The lower panel reports the p-values of the LM test for an extra regime, the in-sample and out-of-sample values of the logarithm of the quasi-likelihood function, and the maximum and minimum values of the sample autocorrelation functions of the in-sample and out-of-sample residuals from order 1 to 200, respectively.

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LM test for extra regime (p-value) 0.0000 0.3765

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maximum ACF

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minimum ACF

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